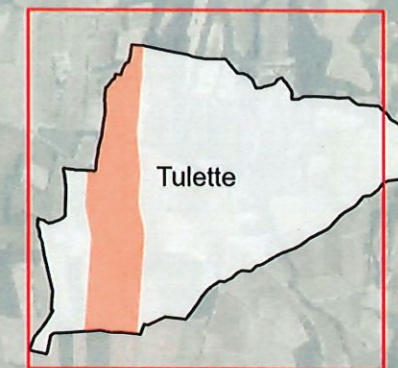




Plan de situation



0 0,5 1 2 km

